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A retraining methodology for enhancing agent intelligence

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8 Abstract

9 Data mining has proven a successful gateway for discovering useful knowledge and for enhancing business intelligence in a range of
10 application fields. Incorporating this knowledge into already deployed applications, though, is highly impractical, since it requires recon-
11 figurable software architectures, as well as human expert consulting. In an attempt to overcome this deficiency, we have developed Agent
12 Academy, an integrated development framework that supports both design and control of multi-agent systems (MAS), as well as “agent
13 training”. We define agent training as the automated incorporation of logic structures generated through data mining into the agents of
14 the system. The increased flexibility and cooperation primitives of MAS, augmented with the training and retraining capabilities of Agent
15 Academy, provide a powerful means for the dynamic exploitation of data mining extracted knowledge. In this paper, we present the
16 methodology and tools for agent retraining. Through experimented results with the Agent Academy platform, we demonstrate how
17 the extracted knowledge can be formulated and how retraining can lead to the improvement – in the long run – of agent intelligence.
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19 *Keywords:* Data mining; Multi-agent systems; Agent intelligence; Training; Retraining
20

21 1. Introduction

22 In a highly complex and competitive business environ-
23 nment, companies must take swift, yet fit decisions that rely
24 on corporate logic and domain knowledge. Diffusing, how-
25 ever, this knowledge into the software processes of the
26 company is a difficult task, which requires reconfigurable
27 software architectures and human expert involvement. A
28 unified approach for discovering useful corporate knowl-
29 edge and incorporating it into the company’s software
30 would therefore be highly desirable.

31 The most dominant solution for discovering *non-trivial,*
32 *implicit, previously unknown and potentially useful* [8]
33 knowledge is Data Mining (DM), a technology developed
34 to support the tremendous data outburst and the impera-
35 tive need for the interpretation and exploitation of massive

data volumes. DM issues concerning data normalization, 36
algorithm complexity and scalability, result validation 37
and comprehension have already been successfully dealt 38
with [1,14,26], while numerous approaches have been 39
adopted for the realization of autonomous and versatile 40
DM tools, which foster all the appropriate pre- and post- 41
processing steps that constitute the process of Knowledge 42
Discovery in Databases (KDD) [6,8,20]. The ultimate goal 43
of DM is the extraction of a *valid* knowledge model (i.e., 44
Decision Rules, Decision Tree, Association Rules, Clus- 45
ters, etc.) that best describes the trends and patterns that 46
underlie in the data. 47

On the other hand, despite the support corporate soft- 48
ware provides on process coordination and data organiza- 49
tion, it often – especially legacy software – lacks advanced 50
capabilities, resulting therefore in decreased company com- 51
petitiveness. The increasing demand for sophisticated soft- 52
ware that comprises of collaborative, yet autonomous, 53
units to regulate, control and organize all distributed activ- 54
ities involved in the company processes, has oriented AI 55

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56 researchers towards the employment of Agent Technology
57 (AT) in a variety of disciplines [15,27]. The versatility and
58 generic nature of the multi-agent technology paradigm
59 has indicated that problems which are inherently distribut-
60 ed or require the synergy of a number of distributed ele-
61 ments for their solution can be efficiently implemented as
62 a multi-agent system (MAS) [9].

63 The coupling of DM and AT principles is therefore
64 expected to provide an efficient gateway for developing
65 highly reconfigurable software approaches that incorporate
66 domain knowledge and provide decision making capabili-
67 ties. The exploitation of useful knowledge extracted by
68 the use of DM may considerably improve agent infrastruc-
69 tures, while also increasing reusability and minimizing cus-
70 tomization costs.

71 Going briefly through related work, attempts to couple
72 DM and AT already exist. Galitsky and Pampapathi [13]
73 use both inductive (DM) and deductive (AT) approaches,
74 in order to model and process the claims of unsatisfied cus-
75 tomers. Deduction is used for describing the behaviors of
76 agents (humans or companies), for which we have complete
77 information, while induction is used to predict the behavior
78 of agents, whose actions are uncertain to us. A more theoret-
79 ical approach on the way DM extracted knowledge can con-
80 tribute to AT performance has been presented by Fernandes
81 [10], who attempts to model the notions of data, informa-
82 tion and knowledge in purely logical terms, in order to inte-
83 grate inductive and deductive reasoning into one inference
84 engine. Kero et al. [17], finally, propose a DM model that
85 utilizes both inductive and deductive components. Within
86 the context of their work, they model the discovery of
87 knowledge as an iteration between high-level, user-specified
88 patterns and their elaboration to (deductive) database que-
89 ries, whereas they define the notion of a meta-query that per-
90 forms the (inductive) analysis of these queries and their
91 transformation to modified, ready-to-use knowledge.

92 Advancing on earlier research efforts to couple the two
93 technologies, we have developed Agent Academy [19,22],
94 an integrated platform for developing MAS architectures
95 and for enhancing their functionality and intelligence
96 through the use of DM techniques.

97 Agent Academy (AA) agents are developed over the
98 Java Agent Development Framework (JADE) [5], which
99 conforms to the FIPA specifications [11]. The MAS ontol-
100 ogies are developed through the Agent Factory module
101 (AF) of AA. Data to be mined are imported to AA in
102 XML format and are forwarded to the Data Miner module
103 of AA, a DM suite that expands the Waikato Environment
104 for Knowledge Analysis (WEKA) tool [26]. The extracted
105 knowledge structures are represented in PMML (Predictive
106 Model Markup Language), a language that efficiently
107 describes clustering, classification and association rule
108 knowledge models [7]. The resulting knowledge is then
109 incorporated into the agents of the MAS by the use of
110 the Agent Training Module (ATM) of AA. All necessary
111 data files (application data, agent behavior data, knowl-
112 edge structures, agent ontologies) are stored into AA's

main database, the Agent Use Repository (AUR). Agents
can be periodically recalled for retraining, since appropri-
ate agent tracking tools have been incorporated into Agent
Academy, in order to monitor agent activity after their
deployment.

It is through retraining that we intent to prove certain
DM techniques can be used to augment agent intelligence
and therefore improve MAS overall performance. The rest
of the paper is organized as follows: Section 2 determines
the formal model for training and retraining agents
through Agent Academy and specifies all the necessary
notations. Section 3 outlines the already developed mecha-
nism for training and retraining, while Section 4 describes
the various training and retraining options for the improve-
ment of agent intelligence and presents some indicative
experimental results. Finally, Section 5 summarizes and
concludes the paper.

2. Formal model for agent (re)training

When a MAS application is deployed by the use of
Agent Academy, the developer has to follow a certain
methodology. These steps are:

- (a) Create the application ontology;
- (b) Create agent behaviors;
- (c) Create agent types, realizing the created behaviors;
- (d) Perform data mining on agent type-specific datasets;
- (e) Generate knowledge models for each agent type;
- (f) Create the agents of the application (of the different agent types);
- (g) Incorporate the extracted knowledge models into the corresponding agents;
- (h) Instantiate the MAS;
- (i) Monitor agents;
- (j) Periodically retrain the agents of the MAS.

Let \mathcal{O} be the ontology of the MAS. Let $A = \{A_1, A_2, \dots, A_n\}$ be the set of attributes described in \mathcal{O} and defined on D , the application data domain. Let $D \subseteq D$ be a set of application data, where each dataset tuple is a vector $t = \{t_1, t_2, \dots, t_n\}$, and $t_i, i = 1, \dots, n$ is a value for the corresponding attribute A_i . Missing values are allowed within t .

In order to initially train a certain type $Ag_i, i = 1, \dots, k$ of application agents, we use a subset of the application dataset, containing the attributes that are relevant to this specific type. We therefore define $D_{IAgi} \subseteq D_{IT}$, where D_{IAgi} is the initial training dataset for agent type Ag_i , and D_{IT} is the initial application dataset. In most cases $D_{IT} = D$. For each Ag_i we perform data mining on the corresponding dataset D_{IAgi} , in order to extract a useful knowledge model $KM_o(o = 1, \dots, p)$ and incorporate it into all $Ag_j(j, j = 1, \dots, m)$, the Ag_r -type agents of the MAS. We then instantiate the MAS and monitor its agents.

In the retraining phase, each agent can be retrained individually. The available datasets include: the initial dataset

167 D_{IT} , a new non-agent dataset¹ D_{NAgi} , and all the datasets
 168 $D_{Agi}(j)$, each containing the tuples representing the actions
 169 (decisions) taken by the respective agent. It must be denot-
 170 ed that $D_{Agi} = D_{Agi}(1) \oplus D_{Agi}(2) \oplus \dots \oplus D_{Agi}(m)$. The
 171 symbol \oplus represents the concatenation of two datasets,
 172 an operation that preserves multiple copies of tuples. There
 173 are five different options of agent retraining, with respect to
 174 the datasets used:

- 175 (A) $D_{IAgi} \oplus D_{NAgi}$. Retrain the agent using the initial
 176 dataset along with a new, non-agent dataset D_{NAgi} .
 177 (B) $D_{NAgi} \oplus D_{Agi}$. Retrain the agent using a non-agent
 178 dataset D_{NAgi} along with D_{Agi} , a dataset generated
 179 by all the Agi -type agents of the application. AA
 180 agents are monitored and their actions are recorded,
 181 in order to construct the D_{Agi} dataset.
 182 (C) $D_{IAgi} \oplus D_{NAgi} \oplus D_{Agi}$. Retrain the agent using all the
 183 available datasets.
 184 (D) $D_{IAgi} \oplus D_{Agi}$. Use the initial dataset D_{IAgi} along with
 185 the agent generated data.
 186 (E) $D_{IAgi} \oplus D_{Agi}(j)$. Use the initial dataset D_{IAgi} along
 187 with $D_{Agi}(j)$, the generated data of the j th agent.
 188

189 A schematic representation of the training and retrain-
 190 ing procedure is given in Fig. 1:

191 Through AA and its training/retraining capabilities the
 192 user can formulate and augment agents' intelligence. AA
 193 supports a variety of both supervised (classification) and
 194 unsupervised learning (clustering, association rule extrac-
 195 tion) DM techniques, shown in Table 1:

196 3. The training and retraining mechanism

197 In order to enable the incorporation of knowledge into
 198 agents, we have implemented Data Miner as an agent-orien-
 199 ted tool. It is a DM suite that supports the application of
 200 a variety of Classification, Clustering and Association Rule
 201 Extraction algorithms on application-specific and agent-
 202 behavior-specific data (Table 1). Data Miner can also
 203 incorporate the extracted decision models into the AF pro-
 204 duced agents, augmenting that way their intelligence.
 205 Apart from being a core component of the AA platform,
 206 the Data Miner can also function as a standalone DM tool.

207 The mechanism for embedding rule-based reasoning
 208 capabilities into agents is illustrated in Fig. 2.

209 Data, either application-specific or agent-behavior-spe-
 210 cific, enter the module in XML format. Each data file con-
 211 tains information on the name of the agent the file belongs
 212 to and on the decision structure of the agent it will be
 213 applied on. The XML file is then inserted into the *Prepro-*
 214 *cessing Unit* of the Data Miner, where all the necessary
 215 data selection and data cleaning tasks take place. Next,
 216 data are forwarded to the *Miner*, where the user decides

217 on the DM technique, as well as on the specific algorithm
 218 to employ. After DM is performed, the results are sent to
 219 the *Evaluator*, which is responsible for the validation and
 220 visualization of the extracted model. If the user accepts
 221 the constructed model, a PMML document describing
 222 the knowledge model is generated. This document express-
 223 es the referencing mechanism of the agent we intend to
 224 train. The resulting decision model is then translated to a
 225 set of facts executed by a rule engine. The implementation
 226 of the rule engine is realized through the Java Expert
 227 System Shell (JESS) [12], which is a robust mechanism
 228 for executing rule-based agent reasoning. The execution
 229 of the rule engine transforms the Data Miner extracted
 230 knowledge into a living part of the agent's behavior.

231 After the MAS has been instantiated, the user has the
 232 ability to monitor AA agents and their decisions. These
 233 decisions are stored into the AUR. For agent j , data stored
 234 in the AUR constitute the $D_{Agi}(j)$ dataset. The user can
 235 then decide, as mentioned in Section 2, on the dataset s /
 236 he would like to perform retraining on.

4. Augmenting agent intelligence

4.1. Different retraining approaches

239 Retraining is performed in order to either increase or
 240 refine agent intelligence. By reapplying data mining on a
 241 new or more complete dataset, the user expects to derive
 242 more accurate patterns and more efficient associations.

243 The five retraining options with respect to the available
 244 datasets, can be classified into two main approaches: a) the
 245 *type-oriented*, which deals with the augmentation of intelli-
 246 gence of Agi , all the type- i agents (options A–D) and, b) the
 247 *agent-oriented*, which focuses on the refinement of intelli-
 248 gence of an individual agent $Agi(j)$, the j th agent of type i
 249 (option E).

250 It should also be denoted that we differentiate on the
 251 way we define "intelligence improvement", since AA pro-
 252 vides both supervised and unsupervised learning DM tech-
 253 niques. In the case of classification, improvement can be
 254 measured by evaluating the knowledge model extracted
 255 metrics (mean-square error, accuracy, etc.), while in the
 256 case of clustering and association rule extraction intelli-
 257 gence augmentation is determined by external evaluation
 258 functions.

259 The classification algorithms provided by the AA plat-
 260 form are decision tree (DT) extraction algorithms. The
 261 basic prerequisites for the proper application of a DT con-
 262 struction algorithm are the existence of a distinct set of
 263 classes and the availability of training data. All the DT
 264 algorithms supported by the AA platform are *criterion gain*
 265 algorithms, i.e., algorithms that decide on the construction
 266 of the DT, according to the minimization (or maximiza-
 267 tion) of a certain criterion. In the case of ID3 and C4.5, this
 268 criterion is the *information gain* [21], in the case of CLS, it is
 269 *record sorting* [14], and in the case of FLR, the criterion is
 270 the *inclusion measure* [16].

¹ We define a non-agent dataset, as the dataset that contains informa-
 tion on the actions of agents, but has not been produced by them
 (probably data come from a pre-stored application dataset).

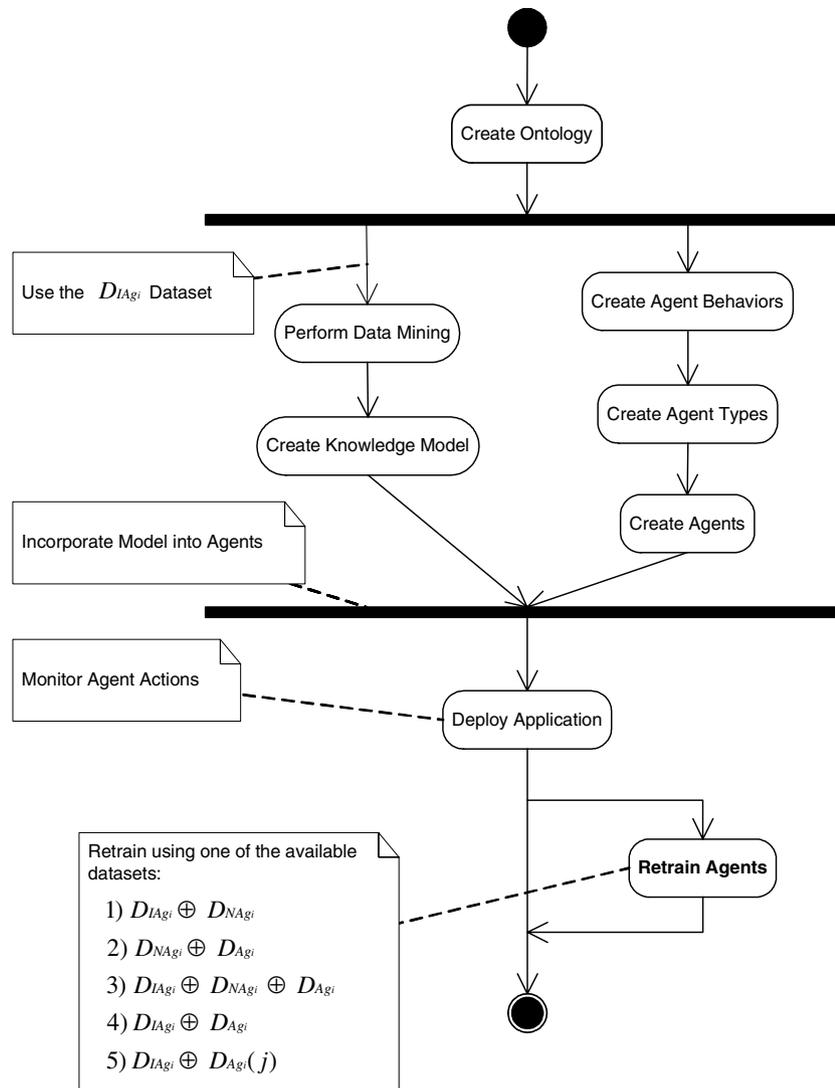


Fig. 1. Training and retraining the agents of a MAS.

Table 1
DM provided techniques and algorithms

Classification	DM technique	
	Association rules	Clustering
ID 3	Apriori	<i>K</i> -means
C 4.5	DHP	PAM
CLS	DIC	EM
FLR ^a	–	<i>κ</i> -Profile

^a The FLR and *κ*-Profile algorithms are novel algorithms, developed within the context of Agent Academy. More information on these algorithms can be found at (Kaburlasos et al. 2003, Athanasiadis et al. 2003) [2].

271 The clustering algorithms provided by AA are partition-
272 ing algorithms (PAs). The objective of PA algorithms is the
273 grouping of the data provided into discrete clusters. Data
274 must have high intra-cluster and low inter-cluster similari-
275 ty. PA algorithms' splitting criterion is the *Euclidean dis-*
276 *tance* between data [18].

277 Finally, the association rule extraction (ARE) algo-
278 rithms provided by AA are mainly focused on transactional
279 datasets. AREs attempt to discover, as their name
280 implies, associations between items. In order for these algo-
281 rithms to decide on the strongest associations, two metrics
282 are considered: *support* and *confidence* [3].

4.2. Training and retraining in the case of supervised learning 283

284 Although the splitting criteria are different, all of the
285 above mentioned classification algorithms are applied in
286 a similar manner. We may focus on the information gain
287 criterion that is employed by the C4.5 and ID3 algorithms,
288 nevertheless the approach followed can be easily adjusted
289 to other classification algorithms of the platform.

The *information gain* expected when splitting dataset *D*
290 with respect to attribute A_i , $A_i \in A$ is given by
291

$$Gain(D, A_i) = Info(D) - Info(D, A_i) \quad (1) \quad 293$$

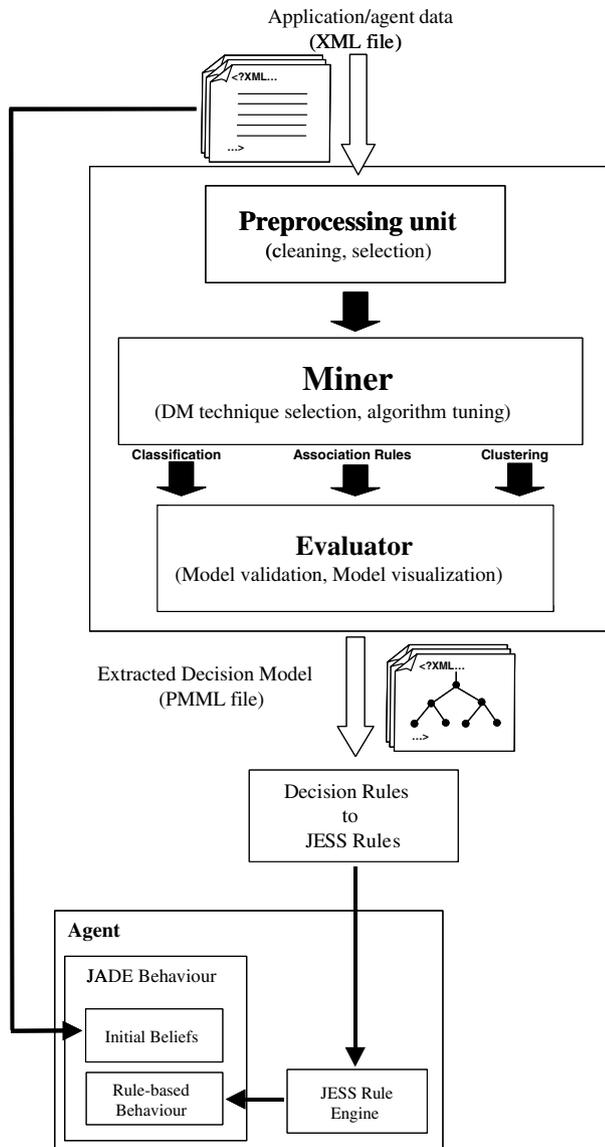


Fig. 2. The agent training/retraining mechanism.

294 $Info(D)$ is the information needed to classify D with respect
 295 to the predefined distinct classes C_i (for $i=1, \dots, o$), and is
 296 given by
 297

$$299 \quad Info(D) = - \sum_{i=1}^o p(I) \log_2 p(I) \quad (2)$$

300 with $p(I)$ the ratio of D tuples that belong to class C_i .

301 $Info(D, A_i)$ is the information needed in order to classify
 302 D , after its partitioning into subsets D_j , $j=1, \dots, v$, with
 303 respect to the attribute A_i . $Info(D, A_i)$, which is also denoted
 304 as the *Entropy* of A , is given by
 305

$$307 \quad Info(D, A_i) = \sum_{j=1}^v \frac{|D_j|}{|D|} * Info(D_j) \quad (3)$$

308 Splitting is conducted on the attribute that yields the max-
 309 imum information gain.

4.2.1. Initial training

310 When training takes place, classification is performed on
 311 D_{IAgi} , the initial dataset for the specific agent type. The user
 312 can decide to split the dataset into a training and a testing
 313 (and/or validation) dataset or to perform n -fold cross-val-
 314 idation. To evaluate the success of the applied classification
 315 scheme, a number of statistical measures are calculated,
 316 i.e., classification accuracy, mean absolute error and confu-
 317 sion matrix. If extracted knowledge model is deemed satis-
 318 factory, the user may accept it and store it, for
 319 incorporation into the corresponding Ag_i -type agents.
 320

4.2.2. Retraining Ag_i

321 In the case of retraining agent-type Ag_i , the relevant
 322 datasets are D_{IAgi} , D_{NAgi} and D_{Agi} . Retraining option C
 323 ($D_{IAgi} \oplus D_{NAgi} \oplus D_{Agi}$) is the most general, containing all
 324 the available data for the specific agent type, while options
 325 A and D are subsets of option C . They are differentiated,
 326 however, since option D is particularly interesting and
 327 deserves special attention.
 328

329 When using datasets D_{IAgi} and D_{NAgi} , the user may
 330 choose among the different retraining options illustrated
 331 in Table 2:

332 The user decides on which knowledge model to accept,
 333 based on its performance. Nevertheless, in the $D_{IAgi} \oplus D_{NAgi}$
 334 case, best model performance is usually observed when
 335 option 3 is selected. The inductive nature of classification dic-
 336 tates that the use of larger training datasets leads to more
 337 efficient knowledge models.
 338

339 The retraining options when the $D_{NAgi} \oplus D_{Agi}$ dataset is
 340 selected are illustrated in Table 3:

341 When retraining an agent with the $D_{NAgi} \oplus D_{Agi}$ dataset,
 342 it is important to notice that the only information we have
 343 on the training dataset D_{IAgi} is indirect, since D_{Agi} is for-
 344 matted based on the knowledge model the agents follow,
 a model induced by the D_{IAgi} dataset. This is why the val-

Table 2
Retraining options for $D_{IAgi} \oplus D_{NAgi}$

	Dataset		Causality
	D_{IAgi}	D_{NAgi}	
Option A-1	Training	Testing	Initial model validation
Option A-2	Testing	Training	Model investigation on data independency
Option A-3	Concatenation and cross-validation		New knowledge model discovery

Table 3
Retraining options for $D_{NAgi} \oplus D_{Agi}$

	Dataset		Causality
	D_{NAgi}	D_{Agi}	
Option B-1	Training	Testing	Indirect initial model validation
Option B-2	Concatenation and cross-validation		New knowledge model discovery

Table 4
Retraining options for $D_{IAgi} \oplus D_{Agi}$

	Dataset		Causality
	D_{IAgi}	D_{Agi}	
Option D-1	Concatenation and cross-validation		More application-efficient knowledge model

345 idation of the initial model is indirect. If the D_{NAgi} -extracted
346 ed model is similar to the D_{IAgi} -extracted model testing
347 accuracy is very high.

348 The fact that D_{Agi} is indirectly induced by D_{IAgi} , does
349 not allow testing D_{Agi} on D_{IAgi} . Nevertheless, concatena-
350 tion of the datasets can lead to more efficient and smaller
351 classification models. Since class assignment within D_{Agi}
352 (the agent decisions) is dependent on the D_{IAgi} -extracted
353 knowledge model, a “bias” is inserted in the concatenated
354 $D_{IAgi} \oplus D_{Agi}$ dataset. Let attribute A_i be the “biased” attri-
355 bute and C_i the supported class. While recalculating the
356 information gain for the $D_{IAgi} \oplus D_{Agi}$ dataset, we observe
357 that the increase of $Info(D)$ is cumulative (Eq. (2)), while
358 the increase of $Info(D, A_j)$ is proportional (Eq. (3)) and
359 therefore $Gain(D, A_i)$ is increased. Clearer decisions on the
360 splitting attributes according to the frequency of occur-
361 rence of A_i in conjunction to C_i are derived, thus leading
362 to more efficient knowledge models. Table 4 illustrates
363 the available retraining options for the corresponding
364 dataset.

365 In the most general case, where all datasets (D_{IAgi} , D_{NAgi}
366 and D_{Agi}) are available, the retraining options are similar to
367 the ones proposed for the already described subsets
368 and similar restrictions apply. Table 5 illustrates these
369 options.

370 4.2.3. Retraining $Ag_i(j)$

371 When retraining a specific agent, the user is interested in
372 the refinement of its intelligence in relation to the working
373 environment. Let us assume that we have trained a number
374 of agents that decide on whether a game of tennis should be
375 conducted, according to weather outlook, temperature,
376 humidity and wind conditions (Weather dataset, [14,26]),
377 and have established these agents in different cities in

Greece (Athens, Thessaloniki, Patra, Chania, etc.). 378
Although all these agents rely initially on a common 379
knowledge model, weather conditions in Thessaloniki differ 380
from those in Chania enough to justify refined knowledge 381
models. 382

In this case, we have the options to perform agent-type 383
retraining. By the use of the $D_{IAgi} \oplus D_{Agi(j)}$ dataset, it is 384
possible to refine the intelligence of the j th agent of type 385
 i . High frequency occurrence of a certain value t_i of attri- 386
bute A_i (i.e., “High” humidity in Thessaloniki, “Sunny” 387
outlook in Chania) may produce a more “case-specific” 388
knowledge model. In a similar to the $D_{IAgi} \oplus D_{Agi}$ manner, 389
it can be seen that an increase of $Info(D, A_j)$ can lead to a 390
different knowledge model, which incorporates instance- 391
specific information. 392

The analysis of different retraining options in the case of 393
Classification indicates that there exist concrete success 394
metrics that can be used to evaluate the extracted knowl- 395
edge models and, thus, may ensure the improvement of 396
agent intelligence. 397

4.3. Training and retraining in the case of unsupervised 398 learning 399

In the case of unsupervised learning, training and 400
retraining success cannot be determined quantitatively. A 401
more qualitative approach must be followed, to determine 402
the efficiency of the extracted knowledge model, with 403
respect to the overall goals of the deployed MAS. 404

4.3.1. Initial training 405

To perform clustering, the user can either split the D_{IAgi} 406
dataset into a training and a testing subset or perform a 407
classes-to-clusters evaluation, by testing the extracted clus- 408
ters with respect to a class attribute defined in D_{IAgi} . In 409
order to evaluate the success of the clustering scheme, the 410
mean square error and standard deviation of each cluster 411
center are calculated. One the other hand, if the user deci- 412
des to perform ARE on D_{IAgi} , no training options are pro- 413
vided. Only the algorithm-specific metrics are specified and 414
ARE is performed. In a similar to classification manner, if 415
the extracted knowledge model (clusters, association rules) 416
is favorably evaluated, it is stored and incorporated into 417
the corresponding Ag_i -type agents. 418

Table 5
Retraining options for $D_{IAgi} \oplus D_{NAgi} \oplus D_{Agi}$

	Dataset			Causality
	D_{IAgi}	D_{Agi}	D_{NAgi}	
Option C-1	Training	Testing	Testing	Initial model validation
Option C-2	Testing	Testing	Training	Model investigation on data independency
Option C-3	Concatenation and training		Testing	New model (more efficient) validation
Option C-4	Concatenation and cross-validation			New knowledge model discovery

4.3.2. Retraining by clustering

Clustering results are in most cases indirectly applied to the deployed MAS. In practice, some kind of an external exploitation function is developed, which somehow fires different agent actions in the case of different clusters. All the available datasets (D_{IAgi} , D_{Nagi} , D_{Agi} and $D_{Agi}(j)$) can therefore be used for both training and testing for *Initial model validation*, *Model Data dependency investigation* and *New Knowledge Model discovery*. A larger training dataset and more thorough testing can lead to more accurate clustering. Often retraining can result in the dynamic updating and encapsulation of dataset trends (i.e., in the case of customer segmentation). Retraining $A_i(j)$ can therefore be defined as a “case-specific” instance of retraining, where data provided by agent j , $D_{Agi}(j)$, are used for own improvement.

4.3.3. Retraining by association rule extraction

The ARE technique does not provide training and testing options. The whole input dataset is used for the extraction of the strongest association rules. Consequently, all available datasets (D_{IAgi} , D_{Nagi} , D_{Agi} and $D_{Agi}(j)$) are concatenated before DM is performed. This unified approach for retraining has a sole goal: to discover the strongest association rules between the items t of D . In a similar to the clustering case manner, retraining $A_i(j)$ can be viewed as a “case-specific” instance of retraining.

5. Experimental results

In order to prove the added value of agent retraining, a number of experiments on Classification, Clustering and ARE were conducted. In this section, three representatives cases are discussed. These experiments are focused mainly on retraining by the use of the D_{Agi} and $D_{Agi}(j)$ datasets and illustrate the enhancement of agent intelligence.

5.1. Intelligent environmental monitoring system

The first experiment was performed for the O₃RTAA System, an agent-based intelligent environmental monitoring system developed for assessing ambient air-quality [4]. A community of software agents is assigned to monitor and validate multi-sensor data, to assess air-quality, and, finally, to fire alarms to appropriate recipients, when needed. Data mining techniques have been used for adding data-driven, customized intelligence into agents with successful results [16].

In this work we focused on the Diagnosis Agent Type. Agents of this type are responsible for monitoring various air quality attributes including pollutants’ emissions and meteorological attributes. Each one of the Diagnosis Agent instances is assigned to monitor one attribute through the corresponding field sensor. In the case of sensor breakdown, Diagnosis Agents take control and perform an estimation of the missing sensor values using a data-driven Reasoning Engine, which exploits DM techniques.

Table 6
Classification accuracies for the Diagnosis Agent

	Dataset		
	D_{IAgi}	D_{Agi}	D_{Val}
Number of instances	11,641	10,000	7414
Initial training	Used	73.58%	71.89%
Retraining	Used		74.66%

One of the Diagnosis Agents is responsible for estimating missing ozone measurement values. This task is accomplished using a predictive model comprised of the *predictors* and the *response*. For the estimation of missing ozone values the predictors are the current values measured by the rest of the sensors, while the response is the level of the missing value (Low, Medium, or High). In this way, the problem has been formed as a *classification* task.

For training and retraining the Ozone Diagnosis Agent we used a dataset, labeled *C2ONDA01* and supplied by CEAM, which contained data from a meteorological station in the district of Valencia, Spain. Several meteorological attributes and air-pollutant values were recorded on a quarter-hourly basis during the year 2001. There are approximately 35,000 records, with ten attributes per record plus the class attribute. The dataset was split into three subsets: one subset for initial training (D_{IAgi}), a second subset for agent testing (D_{Agi}) and another subset for validation (D_{Val}) containing around 40%, 35% and 25% of the data, respectively.

The initial training of the Diagnosis Agent was conducted using Quinlan’s C4.5 [21] algorithm for decision tree induction, using the D_{IAgi} subset. This decision tree was embedded in the Diagnosis Agent and the agent used it for deciding on the records of the D_{Agi} subset. Agent decisions along with the initial application data were used for retraining the Diagnosis Agent (Option D: $D_{IAgi} \oplus D_{Agi}$). Finally, the Diagnosis Agent with the updated decision tree was used for deciding on the cases of the last subset (D_{Val}).

The retrained Diagnosis Agent performed much better compared to the initial training model, are shown in Table 6. The use of agent decisions included in D_{Agi} has enhanced the Diagnosis Agent performance on the D_{Val} subset by 3.65%.

5.2. Speech recognition agents

This experiment was based on the “vowel” dataset of the UCI repository [25]. The problem in this case is to recognize a vowel spoken by an arbitrary speaker. This dataset is comprised of ten continuous primary features (derived from spectral data) and two discrete contextual features (the speaker’s identity and sex) and contains records for 15 speakers. The observations fall into eleven classes (eleven different vowels).

The vowel problem was assigned to an agent community to solve. Two agents $Ag_1(1)$ and $Ag_1(2)$ were deployed to recognize vowels. Although of the same type, the two

Table 7
Speech recognition agents classification accuracy

	$Ag_i(1)$		
	D_{IAgi}	$D_{Ag_i(1)}$	$D_{Va(1)}$
Number of speakers	9	1	1
Initial training	Used	53.03%	46.97%
Retraining	Used		56.06%
	$Ag_i(2)$		
	D_{IAgi}	$D_{Ag_i(2)}$	$D_{Va(2)}$
Number of speakers	9	1	1
Initial training	Used	33.33%	28.78%
Retraining	Used		43.93%

Table 8
The iris recommendation agent success

	Ag_i		
	D_{IAgi}	D_{Ag_i}	Correctly classified
Number of records	113	37	
Initial training	Used	–	83.19%
Retraining	Used		88.67%

517 agents operate in different environments. This is why the
518 dataset was split in the following way: The data of the first
519 nine speakers (D_{IAgi}) were used as a common training set
520 for both $Ag_i(1)$ and $Ag_i(2)$. The records for the next two
521 speakers were assigned to $Ag_i(1)$ and those of the last
522 two speakers were assigned to $Ag_i(2)$.

523 The procedure followed was to evaluate the retraining
524 performance of each on of the agents (Option E: $D_{IAgi} \oplus$
525 $D_{Ag_i(j)}$). After initial training with D_{IAgi} , each of the $Ag_i(1)$
526 and $Ag_i(2)$ was tested on one of the two assigned speakers,
527 while the second speaker was used for the evaluation of the
528 retraining phase. Quinlan's C4.5 algorithm was applied.
529 The classification accuracy, which is similar to that reported
530 by Turney [24], is illustrated in Table 7.

531 It is obvious in this case that retraining using $D_{Ag_i(j)}$
532 leads to considerable enhancement of the agents' ability
533 to decide correctly. The decision models that are induced
534 after the retraining procedure outperformed the validation
535 speakers. The improvement by the mean of classification
536 accuracy was improved by 36% in average.

537 5.3. The iris recommendation agent

538 In order to investigate retraining in the case of cluster-
539 ing, we used the Iris UCI Dataset [25], a dataset widely
540 used in pattern recognition literature. It has four numeric
541 attributes describing the iris plant and one nominal attri-
542 bute describing its class. The 150 records of the set were
543 split into two subsets: one subset (75%) for initial training
544 (D_{IAgi}) and a second subset (25%) for agent testing (D_{Ag_i}).
545 Classes-to-clusters evaluation was performed on D_{IAgi} and
546 $D_{IAgi} \oplus D_{Ag_i}$ (Option D) and the performance of the result-
547 ed clusters was compared on the number of correctly clas-
548 sified instances of the dataset (Table 8).

Again, retraining with the $D_{IAgi} \oplus D_{Ag_i}$ dataset leads to 549
the improvement of clustering results. 550

The new knowledge models obtained with the above 551
retraining options can be easily incorporated into agents 552
following the already implemented training/retraining 553
mechanism, which is described next. 554

555 6. Conclusions

Work presented in this paper explains how DM tech- 556
niques can be successfully coupled with AT, leading to 557
dynamically created agent intelligence. Moreover, the con- 558
cepts of training and retraining are formulated and special 559
focus is given on retraining, the recursive process of “recall- 560
ing” an agent for posterior training. Through this proce- 561
dure, where DM is performed on new datasets (D_{NAgi} , 562
 D_{Ag_i} and $D_{Ag_i(j)}$), refined knowledge is extracted and 563
dynamically embedded into the agents. The different 564
retraining options in the cases of Supervised and Unsuper- 565
vised Learning are outlined in this paper and experimental 566
results on different types of retraining are provided. Final- 567
ly, the training and retraining mechanism is presented. 568
Based on our research work we strongly believe that data 569
mining extracted knowledge could and should be coupled 570
with agent technology, and that training and retraining 571
can indeed lead to more intelligent agents. 572

573 7. Uncited reference

[23]. 574

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